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INFLUENTIAL OBSERVATIONS IN THE GENERALIZED ANALYSIS OF VARIANCE MODEL

A GENERALIZED MULTIVARIATE ANALYSIS OF VARIANCE MODEL (GMANOVA)

First we describe in this section a generalization of the standard MANOVA (multivariate analysis of variance) model suggested in P o t t h o f f and R o y [10]. This model is also known as the growth curves model, although it is a very general model applying to a variety of multivariate situations. Potthoff and Roy's modification to the MANOVA model is the addition of a within-subject design matrix T describing the structure of an individual curve. The model becomes

$$E(Y) = X B T'$$

$$n \times q n \times m \times p p \times q$$
(1.1)

where each row of Y has a multivariate normal distribution with mean vector \mathbf{y}_i and variance-covariance matrix Σ , and X and T are known n x m and q x p matrices of rank m and p, m < n and p \leqslant q. B is an unknown m x p parameter matrix. Denote as $\mathbf{y}_{(i)}$ the rows of Y, so that $\mathbf{Y}' = (\mathbf{y}_{(1)}, \ \mathbf{y}_{(2)}, \ \cdots, \ \mathbf{y}_{(n)})$. The matrix X in the model (1.1) is the usual destan matrix,

The matrix X in the model (1.1) is the usual design matrix, consisting of indicator variables specifying treatment group and possible covariates. For example, in the m-group case with n_1 subjects per group (1-way analysis of variance)

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$$\mathbf{x'}_{\mathbf{m} \times \mathbf{n}} = \begin{bmatrix} \mathbf{1'}_{\mathbf{n}_{1}} & \mathbf{0'} & \cdots & \mathbf{0'} \\ \mathbf{0'} & \mathbf{1'}_{\mathbf{n}_{2}} & \cdots & \mathbf{0'} \\ \vdots & \vdots & \ddots & \vdots \\ \mathbf{0'} & \mathbf{0'} & \mathbf{1'}_{\mathbf{n}_{m}} \end{bmatrix}$$

where $t_{n_i}^1$ denotes an $n_i \times 1$ vector of unities in the design matrix. Very often in growth curve applications T is a matrix whose rows are powers of the time $t_i : t_{ij} = t_i^{j-1}$

$$T_{q \times p} = \begin{bmatrix} 1 & t_{1} & t_{1}^{2} & \dots & t_{1}^{p-1} \\ 1 & t_{2} & t_{2}^{2} & \dots & t_{2}^{p-1} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & t_{q} & t_{q}^{2} & \vdots & t_{q}^{p-1} \end{bmatrix}$$

For the jth subject we could have the univariate linear model

$$y_{(j)} = T \beta + \xi_{(j)}; \quad j = 1, 2, ..., n,$$
 (1.2)

where var $(\epsilon_{(j)}) = \Sigma$ for every j and $\beta' = (\beta_0, \beta_1, \dots, \beta_{p-1})$. The growth curve associated with the jth individual is of the form

$$E(y) = \beta_0 + \beta_1 t + \beta_2 t^2 + ... + \beta_{p-1} t^{p-1}$$
,

and the generalized least squares estimator of β is

$$\beta = (T' \Sigma^{-1} T)^{-1} T' \Sigma^{-1} Y_{(j)}$$

We suppose that $\beta = (\beta_{io}, \beta_{i1}, \dots, \beta_{i,p-1})'$ when the subject falls in the ith group. In this 1-way MANOVA situation the parameter matrix

We rewrite the growth curves model (1.1) by putting it into the vector form. Let us define the matrix operation vec, which rearranges the columns of a matrix underneath each other. Thus, for example, vecY' = y'(1), y'(2), ..., y'(n)' is an nq x 1 vector and vecB' = $(\beta'(1), \beta'(2), \ldots, \beta'(m))$ ' is a pm x 1 vector, where y(i) is the ith row of Y and $\beta(j)$ is the jth row of B. Since we want to put the rows of Y underneath each other, we write first E(Y') = TB'X' and note that vec(TB'X') = (XoT) vecB', where XoT is the Kronecker product of X and T. Therefore we have the generalized linear model defined by the following equations

$$E(\text{vecY'}) = (X \otimes T) \text{vecB'} \tag{1.3}$$

and

$$cov(vecY') = Iw\Sigma,$$

where $\Sigma = \text{cov } y_{(i)}$ for every i = 1, 2, ..., n. Let us suppose, first, that Σ were known. Then the BLUE (best linear unbiased estimate) for vecB' is

$$\operatorname{vecB'} = [(X \otimes T)' (I \otimes \Sigma)^{-1} (X \otimes T)]^{-1} (X \otimes T)' (I \otimes \Sigma)^{-1} \operatorname{vecY'}$$

$$= [(X'X)^{-1} X' \otimes (T'\Sigma^{-1}T)^{-1} T'\Sigma^{-1}] \operatorname{vecY'}$$
(1.4)

which is equivalent to

$$\hat{\mathbf{B}} = (\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathsf{T}}\mathbf{Y}\mathbf{\Sigma}^{-1}\mathbf{T}(\mathbf{T}^{\mathsf{T}}\mathbf{\Sigma}^{-1}\mathbf{T})^{-1}$$
(1.5)

The covariance matrix of the elements of \hat{B} is given as

$$cov(vec\hat{B}) = (X'X)^{-1} \otimes (T'\Sigma^{-1}T)^{-1}$$
(1.6)

Let us consider the estimation of estimable linear functions of the form CBD, where C and D are known matrices of order $g \times m$ and $p \times v$ respectively. This can be written in vector form as $vec(D'B'C') = (C \otimes D')vecB'$. The BLUE for the estimable function $(C \otimes D)vecB'$ is

$$(\operatorname{Cop'}) [(\operatorname{X'X})^{-1} \operatorname{X'o}(\operatorname{T'} \operatorname{\Sigma}^{-1} \operatorname{T})^{-1} \operatorname{T'} \operatorname{\Sigma}^{-1}] \text{ vecy'}$$

which means that

$$C\widehat{B}D = C(X'X)^{-1}X'Y\Sigma^{-1}T(T'\Sigma^{-1}T)^{-1}D$$
 (1.8)

is the BLUE of CRD. The covariance matrix of $(C\otimes D')$ vec \hat{B}' is directly computed to be

$$(C \otimes D') [(X'X)^{-1} \otimes (T'\Sigma^{-1}T)^{-1}] (X' \otimes D)$$

$$= C(X'X)^{-1} C' \otimes D' (T'\Sigma^{-1}T)^{-1} D$$
(1.9)

In practice Σ is usually unknown and should be estimated. Let us reparametrize the model (1.1) for a while so that Γ = BT'. Then we have an ordinary multivariate linear model E(Y) = XF, where Γ' is restricted to the space spanned by the columns of T. The general theory of multivariate linear models shows (see e.g. A r n o 1 d [2], p. 350) that

$$\hat{\Sigma} = \frac{1}{n-m} (y - x \hat{\Gamma})'(y - x \hat{\Gamma})$$
 (1.10)

is an unbiased estimate of Σ and is independent of $\hat{\Gamma}=(x'x)^{-1}x'Y$. In fact $\hat{\Sigma}$ follows the Wishart distribution $W_q(n-m,\frac{1}{n-m},\Sigma)$ with n-m degrees of freedom. If we replace Σ by $\hat{\Sigma}$ in (1.5) and (1.8), we obtain an empirical estimate for B:

$$\tilde{\mathbf{E}} = (\mathbf{X}'\mathbf{X})^{-1} \mathbf{X}' \mathbf{Y} \hat{\mathbf{E}} \mathbf{T} (\mathbf{T}' \hat{\mathbf{E}} \mathbf{T})^{-1}. \tag{1.11a}$$

and for CBD:

$$CBD = C(X'X)^{-1}X'Y\hat{\Sigma}^{-1}T(T'\hat{\Sigma}^{-1}T)^{-1}D$$
 (1.11b)

In a similar way we obtain empirical estimates for the covariance matrices of these estimators by replacing Σ by $\hat{\Sigma}$ in the expressions (1.6) and (1.9). K h a t r i [6] showed that \hat{B} is the maximum-likelihood (ML) estimate of B with the property that

$$|(Y - XBT')'(Y - XBT')|$$
 is minimum at $B = \hat{B}$ 1.12

However, \tilde{B} is no longer BLUE. Note that $\hat{\Sigma}$ is not the ML estimate of Σ ; the ML estimate under the normality assumption (K h a t r i [6]) is

$$\hat{\Sigma}_{ML} = \frac{1}{n}S + \frac{1}{n}(\hat{\Gamma} - \hat{B}T')'X'X(\hat{\Gamma} - \hat{B}T')$$

where S = Y' $[I - X(X'X)^{-1}X']Y$ and $\hat{\Gamma} = (X'X)^{-1}X'Y$. Generally CBD is an unbiased estimator of CBD for all symmetric distributions of Y. Although \hat{B} is not BLUE, $\hat{\Sigma}$ is a consistent estimator of Σ and if n is large, $\hat{\Sigma}$ would be near Σ , and \hat{B} would be near the BLUE.

2. INFLUENCE OF A PART OF DATA

We are interested in the effect of deleting a part of measurements from data. Let \hat{B} be the estimate of B based on full data and let \hat{B}_A be an alternative estimator based on a subset of data. The subset of data can be obtained by deleting observations (some rows of Y), by deleting measurements at a given time-point (certain columns of the observation matrix Y and corresponding rows of T) or by deleting any other subset of measurements from the data. In this application the influence of deleting measurements at given time-points is of primary interest, but we will consider the problem of assessing the influence more generally.

Let I be an s vector of indices that specify the incomplete observations. $Y_{(I)}$ denote the observations, where no measurements are deleted. $Y_{(I)}$ can also be empty. Let Y_{I} denote that set of observations from which some measurements are deleted. Further, we partition Y_{I} such that Y_{IJ} contains the deleted measurements and $Y_{I(I)}$ the rest of the data contained in Y. For

example, data on bulls born in 1966 contain 208 bulls measured at 12 time-points. If we delete for 10 bulls measurements at the ages of 90 and 120 days, Y_{IJ} will be a 10 x 2 matrix and $Y_{I(J)}$ a a 10 x 10 matrix. The growth curve model (1.1) can be expressed as a set of models as follows

$$E(Y_{(I)}) = X_{(I)}BT'$$
 $E(Y_{(J)}) = X_{1}BT'K$
(2.1)

and

$$E(Y_{IJ}) = X_{I}BT'\bar{K},$$

where $X_{(I)}$ is the n_1 x m known across-individuals design matrix for complete observations and X_I is the n_2 x m design matrix for incomplete observations. The matrices B and T are the same as in model (1.1) K is a q x q_1 incidence matrix of zeroes and ones which indicate the times with measurements for cases indexed by I. Correspondingly \bar{K} is a q x $(q-q_1)$ incidence matrix indicating the times with missing measurements. When measurements at the ages of 90 and 120 days are deleted, \bar{K} is as follows

and K is a 13 x 11 matrix of zeroes and ones. Note that KK' + $\overline{\text{KK'}} = \text{I}_{13 \times 13}$. Denoting $\text{vecY'}_{[I]} = \underline{y}_1$, $\text{vecY'}_{\underline{\text{I}}(J)} = \underline{y}_2$ and $\text{vexY'}_{\underline{\text{I}},J} = \underline{y}_3$ we may write the model as follows

$$\begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} \begin{pmatrix} x_{(I)} \otimes T \\ x_{I} \otimes K'T \\ x_{I} \otimes \overline{K}'T \end{pmatrix} \text{ vecB' + vecE'}$$
 (2.2)

Let us further denote $K'T = T_{(J)}$, $\overline{K}'T = T_{J}$, and $K'\Sigma K = \Sigma$ where "(J)" denotes the indeces of cases deleted from the data. If χ_3 is deleted from data, one obtains

$$vec\tilde{B}'_{(IJ)} = [x'_{(I)}x_{(I)}^{*} \otimes T'^{\Sigma^{-1}}T + \\ + x_{I}^{*}x_{I}^{*} \otimes T'_{(J)}^{*} \sum_{(J)}^{-1} T_{(J)}^{*} \int_{-1}^{1} [(x_{(I)}^{*} \otimes \Sigma^{-1}T)' y_{I} + \\ + (x_{I}^{*} \otimes \Sigma_{(J)}^{-1} T_{(J)}^{*})' y_{2}]$$

$$(2.3)$$

Substituting S into (2.3) in place of Σ yields the estimate $\tilde{B}_{(IJ)}$ for B, when Y_{IJ} is deleted from the data. The empirical influence function is now

$$IF(IJ) = \tilde{B} - \tilde{B}_{(IJ)}$$
 (2.4)

When Σ = I, we can derive convenient matrix formulas for the difference \hat{B} - $\hat{B}_{(IJ)}$. However, in this connection we do not consider this an important special case.

2.1. Measuring Influence at the Design Stage

In order to obtain a measure of information we compare traces of covariance matrices. Although measurements indexed by IJ are unavailable, the proportion of change in the trace of covariance matrix of the estimator of (CmD')vecB' can be defined as

$$I_{(IJ)}(CBD) = \frac{trV(C\widehat{B}_{(IJ)}D - trV(C\widehat{B}D)}{trV(C\widehat{B}D)}$$
(2.5)

Note that $CBD = \{ \underline{c}'_{(i)} B \underline{d}_{j} \}$, where $C = (\underline{c}_{(1)}, \underline{c}_{(2)}, \ldots, \underline{c}_{(g)})$ and $D = (\underline{d}_{1}, \underline{d}_{2}, \ldots, \underline{d}_{v})$. However, we adopt a slightly different approach, which is more flexible and more simple. We calculate information on every $\underline{c}'_{(i)} B \underline{d}_{j}$ according to the formula (2.5), and denote it as

$$I_{(IJ)}(\hat{c}'_{(i)}Bd_{j}) = \frac{\left[\hat{c}_{(i)}\otimes d_{j}\right]' \left[v(\hat{b}_{(IJ)}) - v(\hat{b})\right] \left[\hat{c}_{(i)}\otimes d_{j}\right]}{\left[\hat{c}_{(i)}\otimes d_{j}\right]' v(B) \left[\hat{c}_{(i)}\otimes d_{j}\right]} (2.6)$$

As information measure for CBD could be defined as a weighted sum of the information measures (2.6). If all elements of CBD

are of equal interest, then the arithmetic mean of $I_{(IJ)}(c'_{(i)}^{Bd})$ would be appropriate:

$$I_{(IJ)}(CBD) = \sum_{i=1}^{9} \sum_{j=1}^{v} I_{(IJ)}(c'_{(i)}Bd_{(j)})/(gv)$$
 (2.7)

Therefore with respect to the parameter matrix B, the information contained in the measurements indexed by IJ is simply the average of information figures of the elements of B. We suggest calculating the information matrix

$$IM_{(IJ)}(B) = \{I_{(IJ)}(\beta_{ij})\}$$
 (2.8)

which proves a useful statistic. Looking at this matrix we can see the information contained in the observations indexed by IJ with respect to every element of B. We can easily set that

$$I_{(IJ)}(g_{(i)}^{l})^{Bd_{j}} = g_{(i)}^{l}IM_{(IJ)}(g_{j})^{d}$$
 (2.9)

Ghosh [5] suggested a kind of measure similar to that in (2.6) in the context of ordinary linear models.

2.2. Influence at the Inference Stage

perhaps the most popular influence measure at the inference stage in the context of regression models is the distance measure proposed by Cook [4]. No similar measure can be used straightforwardly in a growth curves model. In order to derive a measure for influence suitable in multivariate situations, we consider first testing the hypothesis

$$H_{\rm C}$$
 : CBD = M (2.10)

in the model

$$E(\text{vecY'}) = (X \otimes T) \text{vecB'}$$
 (2.11)

The hypothesis (2.10) can be expressed equivalently by

$$(C \otimes D') \text{ vecB'} = \text{vecM'}$$
 (2.12)

In order to simplify notation we choose M=0 in the sequel, If necessary (CmpD')vecB' could easily be replaced by (CmpD')vecB' - vecM' in the following formulas. If Σ were known, we could use the ordinary χ^2 statistic known from the theory of linear models. If we denote CmpD' = K', we have

$$x^{2} = (K' \text{vecB}') \cdot \{K' \cdot (x \otimes T) \cdot (I \otimes \Sigma)^{-1} (X \otimes T)^{-1} K\}^{-1} (K' \text{vecB}') =$$

$$= (K' \text{vecB}) \cdot \{[C(X'X)^{-1}C']^{-1} \otimes [D'T'\Sigma^{-1}T)^{-1}D]\} (K' \text{vecB}) =$$

$$= \text{tr} \{S_{H}[D'(T'\Sigma^{-1}T)^{-1}D]^{-1} \qquad (2.13)$$

where

$$s_H = (c\hat{B}D)![c(x'x)^{-1}c!]^{-1}(c\hat{B}D)$$
 (2.14)

It is well-known that under Π_0 : CBD = 0 the statistic (2.13) follows the central x^2 distribution with s and n-mp degrees of freedom, where s = gv/ is the number of rows in CDD being full row rank. In certain cases Σ might be known from other experiments, and this "estimate" could be used in place of Σ . Perhaps in some appplications there are good reasons for the use of σ^2 I in place of Σ . Usually, however, Σ is unknown.

Now we consider testing the hypothesis (2.12), when Σ is unknown. As noted in the preceding section. $\hat{\Sigma}$ defined in (1.10) is an unbiased estimator of Σ in the restricted linear model

$$E(Y) = XI$$
 2.15

where Γ = BT'. Otherwise the assumptions are the same as in the model (1,1). It is known (e.g. M u i r h e a d [9], p. 430) that the maximum likelihood estimates of Γ and Σ in the model are $\hat{\Gamma} = (\text{X'X})^{-1}\text{X'Y}$ and $(1/n)\text{S} = (1/n)\text{Y'}[\text{I-X(X'X)}^{-1}\text{X']}\text{Y}$. Moreover $(\hat{\Gamma}, S)$ is sufficient for (Γ, Σ) . The maximum likelihood estimates Γ and S are independently distributed and $S \sim W_{\text{Q}}(n-m, \Sigma)$. Since (1/n)S is the ML estimate of Σ in the model (2.15), (1/n)S is a consistent estimator of Σ , or in other words (1/n)S converges in probability to Σ as n increases without limit. We write $(1/n)\text{S}^P + \Sigma$ as $n + \infty$. This result can also be proved using the weak law of large members

(Arnold [2], p. 365) and the fact that $S \sim W_q$ (n - m, Σ). Naturally the unbiased estimator $\hat{\Sigma}$ is also consistent.

If we substitute $\hat{\Sigma}_{ML}$ for Σ in the expression of the statistic (2.13), we no longer know the distribution of the resulting statistic. However, the asymptotic distribution of this statistic can be obtained.

After this substitution we have

$$(K' \text{vecB})' \{ K' [(X \otimes T)' (I \otimes \hat{\Sigma}_{ML})^{-1} (X \otimes T)]^{-1} K \}^{-1} (K' \text{vecB}')$$
 (2.16)

which is the Wald Statistic for testing H $_{\rm O}$: K'vecB' = Q (see e.g. Silvey [15], p. 116). Wald [17] showed that under the null hypothesis (2.16) is asymptotically distributed as $\chi^2(s)$, where s is the number of rows in K'. We noted above that (1/n)s is a consistent estimator of Σ (and also $\hat{\Sigma}$ = [1/(n - m)]s). Since $\hat{\Sigma}_{\rm ML}$ is a consistent estimator of Σ , the estimators $\Sigma_{\rm ML}$ and $\hat{\Sigma}$ are asymptotically the same. We substitute $\hat{\Sigma}$ for $\hat{\Sigma}_{\rm ML}$ in (2.16), which yields the statistic

$$Q_n = (n - m)tr(S_H S_E^{-1})$$
 (2.17)

where S_H is as in (2.13) and

$$S_{E} = D'(T'S^{-1}T)^{-1}D (2.18)$$

Not it is easy to see that also

$$Q_{\rm p} \sim \chi^2(s)$$
 (2.19)

asymptotically, when H_0 is true. We call W_n the Wald Statistic. Kleinbaum [7] proposed this approach for testing linear hypotheses in this generalized growth curve model.

To determine the degree of influence the measurements indexed by IJ have in the estimate \tilde{B} , we suggest the measure defined by

$$D_{(IJ)}(CBD) = tr(S_H S_E^{-1})$$
 (2.20)

where

$$s_{H} = [C(\tilde{B} - \tilde{B}_{(IJ)})D]'[C(X'X)^{-1}C']^{-1}[C(\tilde{B} - \tilde{B}_{(IJ)})D]$$
 (2.21)

We again adopt the same approach as in introducing the design stage measure and calculate first the influence of every $C'(i)^{\mathrm{Bd}}i$. Thus we have

$$D_{(IJ)}(g'_{(i)}Bd_{j}) = \frac{\left[c'_{(i)}(\tilde{B}-\tilde{B}_{(IJ)})d_{j}\right]^{2}}{c'_{(i)}(x'x)^{-1}g_{(i)}d'_{(I'}s^{-1}_{(IJ)}Dd_{j}}$$
(2.22)

The following relation holds between these measures:

$$D_{(IJ)}(g'_{(i)}Bd_{j}) = I_{(IJ)}(g'_{(i)}Bd_{j})$$

$$\cdot \frac{\left[\underline{c}'_{(i)}^{(\tilde{B}-\tilde{B}_{(IJ)}\underline{d}_{j})}^{\tilde{d}_{j}}\right]^{2}}{v(\underline{c}'_{(i)}^{\tilde{B}_{(IJ)}\underline{d}_{j})} - v(\underline{c}'_{(i)}^{\tilde{B}\underline{d}_{j})}}$$
(2.23)

Suppose now for a moment that Σ = I. Then we can write

$$[c'_{(i)}(\hat{B} - \hat{B}_{(IJ)})d_{j}]^{2} = (2.24)$$

$$= (c'_{(i)} \otimes d'_{j}) (X'X \otimes T'T)^{-1} (X_{I} \otimes T_{J})'AA' (X_{I} \otimes T_{J}) (X'X \otimes T'T)^{-1} (c_{(i)} \otimes d'_{j}),$$

where

$$A = (I - H_{IJ})^{-1} [vecY'_{(IJ)} - (X_{I} x_{J}) vecB']$$
 (2.25)

It can easily be shown that $E(AA') = (I - H_{IJ})^{-1}$. Therefore (2.6) and (2.24) yield the result

$$E[D_{(IJ)}(\underline{c}'_{(i)}B\underline{d}_{j})] = I_{(IJ)}(\underline{c}'_{(i)}B\underline{d}_{j})$$
(2.26)

When Σ = I, the maximum value of $D_{(IJ)}(c_{(1)}^{\dagger}Bd_{j})$ is $A'(X_{I} \otimes T_{J})(X'X \otimes T'T)^{-1}(X_{I} \otimes T_{J})'A$, which is the largest eigenvalue of the matrix $(X_{I} \otimes T_{J})'AA'(X_{I} \otimes T_{J})(X'X \otimes T'T)^{-1}$. Further, it can easily be discerned (see e.g. G h o s h [5]) that

$$E[\max D_{(IJ)}(g'Bg)] = \max I(g'Bg)$$

$$g,g$$

$$g,g$$

$$(2.27)$$

It should be emphasised that the preceding identities do not hold in the case where \hat{B} is not equal to $(x'x)^{-1}x'yT(T'T)^{-1}$.

3. AN EXAMPLE

Now we investigate the influence of deleting measurements at different time-points, when data on 200 bulls born in 1966 are under consideration. A polynomial of third degree was fitted them. In Figure 1 the values of the inference stage influence neasure (2.20) for different ages are given.

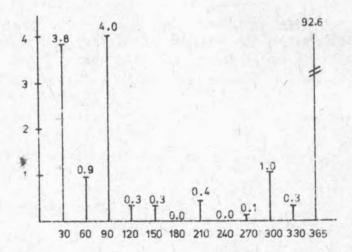


Fig. 1. The values of the influence measure $D_{(.,J)}(B)$ for different time-points when the measurements at the corresponding point are deleted. Data concern bulls born in 1966

When the measurements are equally spaced, it is expected that the observations at the beginning and at the end of the sample period are most influential. This follows from the fact that detecting observations at the ends of the sample period reduces most the variance of \hat{B} (see the identities (2.5) and (2.26)). Note that the statistic (2.17) is the Lawley-Hotelling trace statistic. This is used as a basis for our influence measure, sin-

ce the statistic can be easely interpreted as a distance measure as can be seen from (2.16) and from (2.21). The magnitude of (n-m)D_(IJ)(CBD) may be assessed by comparing it to the probability points of the corresponding Lawley-Hotelling statistic under H_0 : : CBD = 0.

The degree of influence is greatest at the points, 30, 90 and 365 days of ages. For economic and other practical seasons, measurements at the ages 30, 90, 120 and 150 days were not taken after the year 1970. If we delete these ages from the data on bulls born in 1966, the degree of influence $D_{(1)}(B) = 302.7$, where J = (1, 3, 4, 5). Deleting the first three ages 30, 60 and 90 days yields the value 3593.4 for D(1)(B), but dropping out the four ages 60, 120, 150 and 240 gives the value 0.5. The 95% significance point of the corresponding Lawley-Notelling statistic is 0.06. Therefore 0.5 is highly significant. If 4 weighing times must be deleted, one natural approach is to find such points which have least influence on the estimates. Finding the minimum is not straightforward since some time-points may be jointly influential but individually uninfluential, and conversely: some time-points may be individually influential but jointly uninfluential.

However, there might also be some practical side-conditions for selecting weighing times. On the other hand, it may be important to attain a good fit to data in individual bulls specially at a given age interval. Of course, the influence of a given set of measurements also depends on the mathematical form of a chosen growth curve, Therefore this influence analysis serves as a means for comparing the robustness of various models to missing measurements and to different study designs (i.e. sets of target ages).

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OBSERWACJE WPŁYWOWE W UOGÓLNIONEJ ANALIZIE MODELU WARIANCJI

Podano opis modelu GMANOVA wielowymiarowej analizy wariancji (zwanego czasem modelem krzywych wzrostu).

Dyskutowano problemy analizy skutków występowania wpływowych wyników obserwacji na własności estymatorów. Okazało się, że skutki te są różne w zależności od kształtu estymowanej funkcji parametrycznej.

Proponuje się pomiar tych skutków w fazie planowania eksperymentów oraz w fazie analizy danych eksperymentalnych. Wyniki analizy zilustrowano rezultatami badań eksperymentalnych z zakresu hodowli zwierząt.